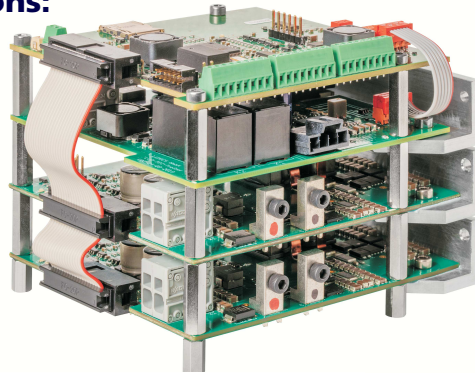




## LuOcean Driver Kit Rev.5 - Laser Driver Part

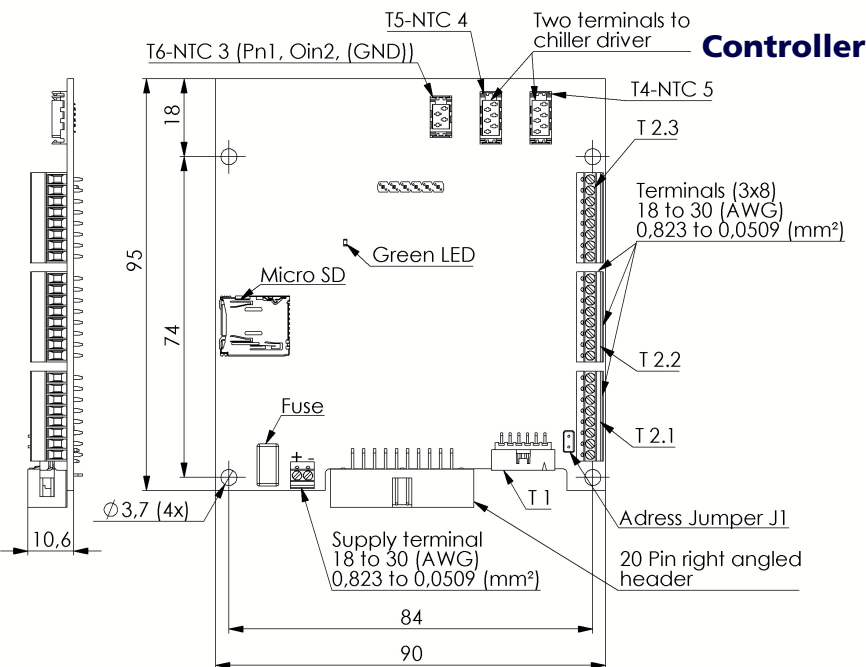
### Features & Functions & Options:

- Full digital control
- Current range 0.3A to 28 A
- Pilot on/off & intensity control
- Pulse width down to 200µs
- Duty cycle range 1% to 99%
- Laser off after error/interlock
- External analog synchronisation
- Shut down in case of overheating
- Fan & heat sink for laser/chiller driver
- Wall plug efficiency 96%

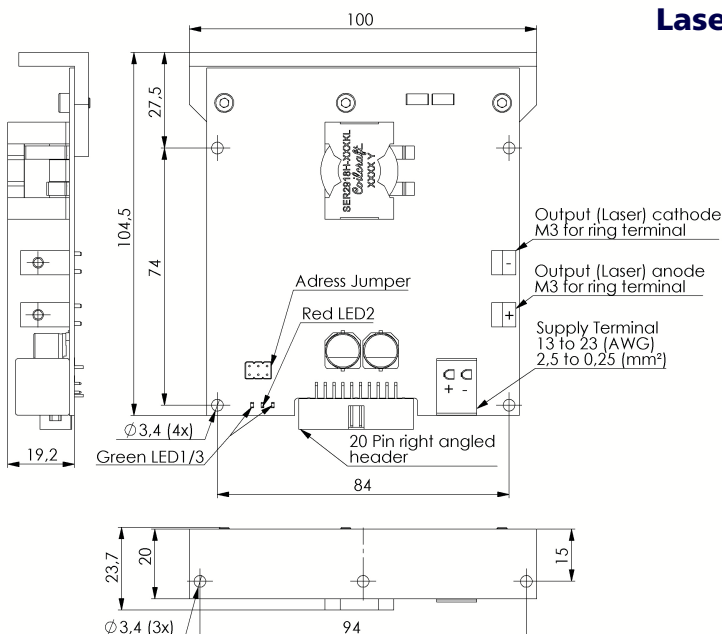


### Drawing (Dimension)

#### Controller



#### Laser Driver



### Description:

The LuOcean™ driver kit is designed for OEM manufacturers requiring a digital interface to the LuOcean™ diode laser series. It provides laser driver and temperature control with a laser driver, chiller driver and a cooling unit. The standard RS232 programming interface and build-in protective features provide the opportunity to simplify development and manufacturing.

### Benefits:

- Laser short circuit protection
- External interlock signal
- Digital access to all laser module sensors
- Full laser diode protection
- Synchronizing up to 6 LD and 2 TEC drivers
- Variable configuration

### Controller Terminal T1 Description

| Pin | Term. | Sensor/Control Function                            | Terminal |
|-----|-------|--|----------|
| 1   | T1    | Vs = 12 V for Fiber sensor / Monitor diode cathode |          |
| 2   | T1    | Fiber sensor 1 signal - In                         |          |
| 3   | T1    | GND  |          |
| 4   | T1    | Fiber sensor 2 signal - In                         |          |
| 5   | T1    | Monitor diode signal 1 - In                        |          |
| 6   | T1    | Pilot laser (3/5) V (50 mA) 8 V / 100 mA - Out     |          |
| 7   | T1    | Monitor diode signal 2 - In                        |          |
| 8   | T1    | GND (Pilot) or humidity sensor or digital bus      |          |
| 9   | T1    | GND (NTC)  |          |
| 10  | T1    | Pilot intensity control (0-5)V, pilot off =5V      |          |
| 11  | T1    | NTC1 - In  |          |
| 12  | T1    | NTC2 - In or digital bus                           |          |

### Controller Terminal T2 Description

| Pin | Term. | Sensor/Control Function                       | Terminal |
|-----|-------|---|----------|
| 1   | T2.1  | RS232-TX signal - OUT                         |          |
| 2   | T2.1  | RS232-RX signal - In                          |          |
| 3   | T2.1  | GND RS232 (serial interface common, floating) |          |
| 4   | T2.1  | Interlock signal - In                         |          |
| 5   | T2.1  | Interlock supply - Out (12V or 24 V)          |          |
| 6   | T2.1  | no connection                                 |          |
| 7   | T2.1  | GND   |          |
| 8   | T2.1  | Interlock on - LED Out (3.3V)                 |          |
| 1   | T2.2  | Laser driver 1 on - LED out (3.3V)            |          |
| 2   | T2.2  | Laser driver 2 on - LED out (3.3V)            |          |
| 3   | T2.2  | Laser driver 3 on - LED out (3.3V)            |          |
| 4   | T2.2  | Laser driver 4 on - LED out (3.3V)            |          |
| 5   | T2.2  | Laser driver 5 on - LED out (3.3V)            |          |
| 6   | T2.2  | Laser driver 6 on - LED out (3.3V)            |          |
| 7   | T2.2  | Laser diode monitor 1 (V) module dependent    |          |
| 8   | T2.2  | Laser diode monitor 2 (V) module dependent    |          |
| 1   | T2.3  | GND   |          |
| 2   | T2.3  | Pulse Sync In                                 |          |
| 3   | T2.3  | GND   |          |
| 4   | T2.3  | Pulse Sync Out                                |          |
| 5   | T2.3  | GND   |          |
| 6   | T2.3  | no connection                                 |          |
| 7   | T2.3  | Fan (GND) laser driver                        |          |
| 8   | T2.3  | Fan (+) laser driver                          |          |

**We manufacture diode lasers.**

## General Characteristics (ambient condition)

| Parameter / Conditions  | Symbol                 | Min       | Typ                                 | Max       | Unit | LuOcean Diode Laser Application |
|---|------------------------|-----------|-------------------------------------|-----------|------|---------------------------------|
| <b>Diode Laser Driver Output Voltage Range</b>                                |                        |           |                                     |           |      |                                 |
| Input voltage on DC supply terminal   | V <sub>in</sub>        |           | 48                                  |           | V    | Mini series, M4 series          |
| Output voltage on laser terminal  | V <sub>out</sub>       | 3.5       |                                     | 40        | V    |                                 |
| Input voltage on DC supply terminal   | V <sub>in</sub>        |           | 36                                  |           | V    | Mini series, M4 series          |
| Output voltage on laser terminal  | V <sub>out</sub>       | 3         |                                     | 30        | V    |                                 |
| Input voltage on DC supply terminal   | V <sub>in</sub>        |           | 24                                  |           | V    | Mini series, M4 series          |
| Output voltage on laser terminal  | V <sub>out</sub>       | 2         |                                     | 20        | V    |                                 |
| Input voltage on DC supply terminal   | V <sub>in</sub>        |           | 12                                  |           | V    | Mini series, M4 series          |
| Output voltage on laser terminal (1)  | V <sub>out</sub>       | 1         |                                     | 10        | V    |                                 |
| <b>General Characteristic Diode Laser Driver</b>                              |                        |           |                                     |           |      |                                 |
| Output current on laser terminal in pulsed and cw mode                        | I <sub>out</sub>       | 0.3       |                                     | 28        | A    |                                 |
| Efficiency  | h                      |           | 96                                  |           | %    |                                 |
| Output Current Ripple (10 - 600) KHz at >=1A                                  | I <sub>rms</sub>       |           | 0.1                                 |           | A    |                                 |
| Output Current Ripple (10 - 600) KHz below 1A                                 | I <sub>rms</sub>       |           | 0.2                                 |           | A    |                                 |
| Rise and Fall Time full current range (4)                                     | t <sub>rise</sub>      |           | 0.03                                | 0.15      | ms   |                                 |
| Current Overshoot (2) at >=1A and output voltage >=10% input voltage          | I <sub>err</sub>       |           |                                     | 10        | %    |                                 |
| Current Overshoot (2) at >=1A and output voltage (>7% and <10%) input voltage | I <sub>err</sub>       |           | 10                                  | 20        | %    |                                 |
| Current Overshoot (2) below 1A  | I <sub>err</sub>       |           | 20                                  |           | %    |                                 |
| Current Accuracy (dc to 5 kHz) (3) at >=1A                                    | I <sub>acc_1</sub>     |           |                                     | +2        | %    |                                 |
| Current Accuracy (dc to 5 kHz) (3) below 1A                                   | I <sub>acc_2</sub>     |           | +5                                  |           | %    |                                 |
| Pulse width single current driver   | P <sub>w</sub>         | 200       |                                     |           | μs   |                                 |
| Minimum pulse phase delay between two synchronized pulses                     | P <sub>w</sub>         | 100       |                                     |           | μs   |                                 |
| Pulse duty cycle  | P <sub>dc</sub>        | 1         |                                     | 99        | %    |                                 |
| <b>Controller</b>   |                        |           |                                     |           |      |                                 |
| Supply Voltage / Current without fan  |                        | 12 / <0.8 |                                     | 48 / <0.2 | V/A  |                                 |
| Single shot and pulse train with up to 1000 pulses                            |                        |           | yes                                 |           |      |                                 |
| Current read back, sample rate  |                        |           | 2                                   |           | ms   |                                 |
| Voltage read back, sample rate  |                        |           | 2                                   |           | ms   |                                 |
| Maximum phase shift per number of synchronized pulses                         |                        |           | 20                                  |           | μs   |                                 |
| Maximum phase jitter between synchronized pulses                              |                        |           | 20                                  |           | μs   |                                 |
| RS232 Baud rate   |                        |           | 9600 or 115200                      |           |      |                                 |
| RS232 Data Format   |                        |           | 8 Data Bit / no parity / 1 Stop Bit |           |      |                                 |
| Fan voltage setting for optional heat sink with fan                           | V <sub>fan</sub>       |           | 14 or 26                            |           | V    |                                 |
| Fan current for optional heat sink with fan                                   | I <sub>fan</sub>       |           |                                     | 0.7       | A    |                                 |
| Interlock Signal  | V <sub>interlock</sub> | 11        | 12                                  | 13        | V    |                                 |
| Laser shut down delay after external interlock signal                         | t <sub>d_delay</sub>   |           |                                     | 200       | μs   |                                 |

### Note

(1) Lower driving voltage than 1.3V results in current over shoot of >20%.

It is recommended to add Si schottky diodes in series with the laser diode to increase to driving voltage

(2) Current overshoot is about max. 400μs and typical 200μs long and increases with lower driving voltage, lower duty cycle and lower pul width

(3) Accuracy depends on current

(4) Rise and Fall time increase with driving current

## General Parameters

| Parameter   | Symbol  | Min | Typ | Max | Unit |
|---|---|-----|-----|-----|------|
| Storage temperature (1)   | T <sub>s</sub>  | -10 |     | 55  | °C   |
| Ambient operation temperature (1)   | T <sub>op</sub>   | 0   |     | 45  | °C   |
| Humidity / non-condensing atmosphere  |   |     |     | 80  | %    |
| Compliance (4)  | ROHS / UL94V-0 / EMC certificate with demo housing example according to EN 55011 under evaluation |     |     |     |      |
| <b>Controller</b>   |   |     |     |     |      |
| Cooling   | convection cooling only   |     |     |     |      |
| Signal & control interface terminal 1 to laser module 12 pin double row flat cable socket   |   |     |     |     |      |
| Signal & control Interface terminal 2 to external devices 3x8 way screw terminal block  |   |     |     |     |      |
| Fuse in a box , type Littlefuse 0154002Dr   |   |     |     |     |      |
| <b>Laser Driver</b>   |   |     |     |     |      |
| Cooling optional (heat sink and type (convection or forced air cooling) depends on thermal load, total thermal resistance of build-in heat sink 10K/W |   |     |     |     |      |
| To diode laser one 2 way M3 screw terminal block, type Würth electronic 7461101   |   |     |     |     |      |
| To power supply one 2 way push in clamp terminal block for up to 2.5 sq.mm or 10 AWG , type Wago 2624-1102  |   |     |     |     |      |
| Fuse 30A SMD , type Schurter 3403.0289.23   |   |     |     |     |      |
| <b>Further Options</b>  |   |     |     |     |      |
| Interface cable to LuOcean diode lasers   |   |     |     |     |      |
| Chiller packages for LuOcean diode lasers on request  |   |     |     |     |      |
| Heat sink with fan for laser driver depending on electrical power supplied  |   |     |     |     |      |

### Notes:

(1) Operating temperature and rel. humidity must be chosen in a way that the dewpoint of humid air is below the temperature of the board to avoid condensing of water.

(2) Fan voltage: one operation mode only at 12V when DC supply is 12V and two modes (14V/24V) for >=24V supply

(3) External interlock must be a low current (<1mA) sourcing (mechanical) switch (e.g. door lock). Interlock 12(24)V for 12(>=24)V DC supply

(4) EMC certificate under evaluation.